# Why are Some Problems Difficult to Solve ?

#### Some Problems

- 1. SAT (satisfiability problem)
  - Boolean 식을 TRUE 로 만드는 변수를 찾는 문제

(ex) Find 
$$x_i$$
  $(i = 1, ..., 100)$   
s.t.  $F(x) = \text{TRUE}$   
where  
 $F(x) = (x + \sqrt{x} + \sqrt{x}) \wedge (\overline{x} + \sqrt{x}) \wedge \dots \wedge (x + \sqrt{x} + \sqrt{x})$ 

 $F(\mathbf{x}) = (x_{17} \lor \bar{x}_{37} \lor x_{73}) \land (\bar{x}_{11} \lor x_{56}) \land \dots \land (x_2 \lor \bar{x}_{77} \lor x_{43} \lor \bar{x}_{89})$ 

Search space S

|S| = 2<sup>n</sup>
n = 100 ⇒ 2<sup>100</sup> ≈ 10<sup>30</sup>
1000 strings / sec → 15 billion years (150억년)

Evaluation Function

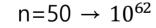
ii worse / better 를 판단하기 어려움

#### Some Problems

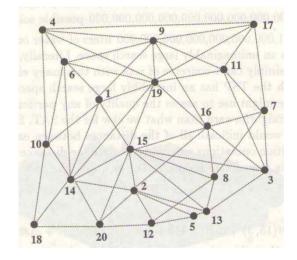
- 2. TSP (travelling salesman problem)
  - 모든 도시를 한번씩 방문하고 돌아오는 순서 결정 문제
  - 최소 시간 or 최단 거리
    - Symmetric TSP: d(i,j) = d(j,i)
    - Asymmetric TSP:  $d(i,j) \neq d(j,i)$
  - Search space

 $n=6 \rightarrow 60$ 

$$|S| = \frac{n!}{2n} = \frac{(n-1)!}{2}$$
  
n=6 \rightarrow 60  
n=7 \rightarrow 360  
n=10 \rightarrow 181,000  
n=20 \rightarrow 10,000,000,000,000



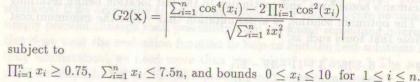
– Evaluation function 해의 worse / better 를 판단할 수 있음



#### Some Problems

- 3. NLP (nonlinear programing problem)
  - 비선형 함수의 최대/최소 값을 찾는 문제

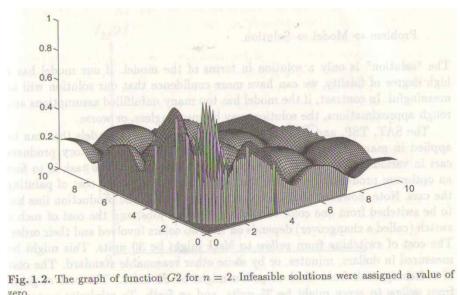
(ex) maximize G2(x)



- Search space 각  $x_i$ 를 0.000001 단위로 분할  $|S| = 10^{7n}$ 

 $n=50 \rightarrow 10^{350}$ 

Evaluation function
 해의 worse / better 를 판단할
 수 있음



# Modeling the Problem

- Problem  $\rightarrow$  Model  $\rightarrow$  Solution
- Car production schedule problem
  - n 개의 color 를 painting
  - Cost of switching
     Yellow -> black: 30, black -> yellow: 80
     Yellow -> Green: 50, .....
  - Find a job sequence to minimize the total cost of switching

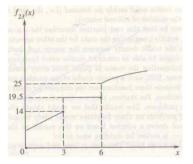
n-city asymmetric TSP

# Modeling the Problem

- Transportation problem
  - *n* warehouses (source)
  - k distribution center (destination)
  - $f_{ij}$ : transportation cost between warehouse *i* and destination

center j ( $i = 1, \dots, n$ ,  $j = 1, \dots, k$ )

$$f_{23}(x) = \begin{cases} 0 & \text{if } x = 0\\ 4 + 3.33x & \text{if } 0 < x \le 3\\ 19.5 & \text{if } 3 < x \le 6\\ 0.5 + 10\sqrt{x} & \text{if } 6 < x, \end{cases}$$



x: quantity of supplies

Find quantity of supplies to minimize the total transportation cost

minimize 
$$\sum_{i=1}^{n} \sum_{j=1}^{k} f_{ij}(x_{ij})$$
,  
subject to  
 $\sum_{i=1}^{k} x_{ij} \leq sour(i)$ , for  $i = 1, 2, \dots, n$ ,  
 $\sum_{i=1}^{n} x_{ij} \geq dest(j)$ , for  $j = 1, 2, \dots, k$ ,  
 $x_{ij} \geq 0$ , for  $i = 1, 2, \dots, n$  and  $j = 1, 2, \dots, k$ ,

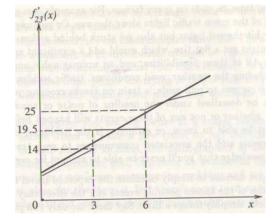
 $x_{ij}$ : quantity from source *i* to destination *j* 

#### Modeling the Problem

- Transportation Problem
  - Approximation

$$f'_{23}(x) = 2.66x + 8.25$$

r LP



- Two approaches
  - 1) Problem  $\rightarrow M \text{ odel }_a \rightarrow Solution \quad {}_p(M \text{ odel }_a)$
  - 2) Problem  $\rightarrow M \text{ odel }_p \rightarrow Solution$   $_a(M \text{ odel }_p)$ *a*: approximated, *p*: precise
  - 일반적으로 2) 가 바람직한 접근 방법

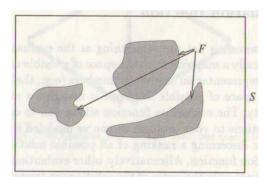
# Basic Concepts

### Search Problem

• Search Problem (Optimization Problem) Given a search space S and its feasible part  $F \subseteq S$ , find  $x \in F$  such that  $eval(x) \leq eval(y)$ 

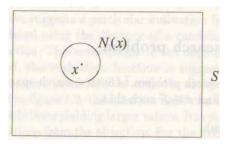
for all  $y \in F$ .

 $rac{} r x$  : global solution



• Neighborhood N(x)

Set of all points of the search space *S* that are **close** in some **measurable sense** to the given point *x* 



(ex) NLP

 $N(x) = \{y \in S : dist \ (x, y) \le \epsilon\}$ dist  $(x, y) = \sqrt{\sum_{i=1}^{n} (x_i - y_i)^2}$  (Euclidean distance)

• Neighborhood N(x)(ex) TSP : 2-swap mapping 3-2-4-1-5  $\chi$ : *N*(*x*): **2-3**-4-1-5 4-2-3-1-5 **1**-2-4-**3**-5 5-2-4-1-3 3-4-2-1-5 3-1-4-2-5 3-5-4-1-2 3-2-1-4-5 3-2-5-1-4 3-2-4-5-1 *n* city TSP:  $\frac{n(n-1)}{2}$  neighbors

• Local optima

eval  $(x) \leq eval (y)$ 

for all  $y \in N(x)$ 

x : local solution (local optimum)

• Local search strategy

Locate solutions within a neighborhood of the current point that have better evaluations

(ex) minimize  $f(x) = x^2$ 

- Size of the neighborhood vs. efficiency of the search
  - Smaller size of neighborhood
    - $\rightarrow$  quick search, local optimum
  - Larger size of neighborhood
    - $\rightarrow$  better decisions, huge computation

### Hill-Climbing Methods

- Hill-climbing procedure
  - Start from a single point (current point)
  - Improve the current point by searching the neighborhood
  - Terminates if no further improvement

```
procedure iterated hill-climber
begin
   t \leftarrow 0
  initialize best
  repeat
      local \leftarrow FALSE
      select a current point \mathbf{v}_c at random
      evaluate \mathbf{v}_c
      repeat
         select all new points in the neighborhood of v_c
         select the point \mathbf{v}_n from the set of new points
            with the best value of evaluation function eval
         if eval(\mathbf{v}_n) is better than eval(\mathbf{v}_c)
            then \mathbf{v}_c \leftarrow \mathbf{v}_n
            else local \leftarrow TRUE
      until local
      t \leftarrow t + 1
      if \mathbf{v}_c is better than best
         then best \leftarrow \mathbf{v}_c
   until t = MAX
end
```

```
t: number of iterations
bal : 해의 개선 여부
best : 최적해
v<sub>c</sub>: current point
v<sub>n</sub>: new point
```

# Hill-Climbing Methods

- Weakness
  - Terminates at solutions that are only locally optimal
  - Depends on the initial configuration
  - Not possible to provide an upper bound for computation time